

PathFinder

Generated by Doxygen 1.8.6

Sun Jun 18 2017 14:30:45

Contents

1	Class Index	1
1.1	Class List	1
2	Class Documentation	3
2.1	AdjacencyList Class Reference	3
2.1.1	Detailed Description	3
2.1.2	Constructor & Destructor Documentation	3
2.1.2.1	AdjacencyList	3
2.1.2.2	AdjacencyList	3
2.1.2.3	AdjacencyList	4
2.1.3	Member Function Documentation	4
2.1.3.1	addEdge	4
2.1.3.2	displayAdjacencyList	4
2.1.3.3	getInfoValue	4
2.1.3.4	getVertexConnectionCount	4
2.1.3.5	getVertexConnections	5
2.1.3.6	getVertexData	5
2.1.3.7	removeEdge	5
2.1.3.8	resizeAdjList	5
2.1.3.9	saveToFile	5
2.1.3.10	setVertexConnections	6
2.1.3.11	size	6
2.1.3.12	updateInfo	6
2.1.3.13	validVertex	6
2.1.3.14	vertexCount	6
2.2	CommunityIdentifier Class Reference	7
2.2.1	Detailed Description	7
2.2.2	Member Function Documentation	7
2.2.2.1	identifyCommunities	7
2.3	DijkstrasAlgorithm Class Reference	7
2.3.1	Member Function Documentation	7

2.3.1.1	singleSourceShortestPath	7
2.4	GraphViz Class Reference	8
2.4.1	Detailed Description	8
2.4.2	Member Function Documentation	8
2.4.2.1	convertKSSPAdjListToDOT	8
2.4.2.2	convertMSTAdjListToDOT	9
2.5	KSimpleShortestPaths Class Reference	9
2.5.1	Detailed Description	10
2.5.2	Member Function Documentation	10
2.5.2.1	kSSP	10
2.5.2.2	kSSPR	10
2.5.2.3	runKSSP	11
2.6	MST Class Reference	11
2.6.1	Detailed Description	12
2.6.2	Member Function Documentation	12
2.6.2.1	calculateMST	12
2.6.2.2	runMST	12
2.7	Parsing Class Reference	13
2.7.1	Member Function Documentation	13
2.7.1.1	getGraphData	13
2.7.1.2	getNamedGraphData	13
2.7.1.3	parseKSSPResults	14
2.7.1.4	parseMSTResults	14
2.7.1.5	removeEdges	14
2.7.1.6	removeVertices	14
2.8	PathInformation Class Reference	15
2.8.1	Detailed Description	15
2.8.2	Constructor & Destructor Documentation	15
2.8.2.1	PathInformation	15
2.8.2.2	PathInformation	15
2.8.3	Member Function Documentation	15
2.8.3.1	equals	15
2.8.3.2	getPath	16
2.8.3.3	getPathAt	16
2.8.3.4	getPathLength	16
2.8.3.5	setPath	16
2.8.3.6	setPathLength	16
2.8.3.7	toString	16
2.9	SearchSpaceReduction Class Reference	17
2.9.1	Detailed Description	17

2.9.2	Member Function Documentation	17
2.9.2.1	keyNeighboringVertices	17
2.9.2.2	searchSpaceReduce	17
2.10	Utility Class Reference	18
2.10.1	Detailed Description	18
2.10.2	Member Function Documentation	18
2.10.2.1	vectorIntersection	18
2.10.2.2	vectorIntIntersection	18
2.10.2.3	vectorToString	19
Index		20

Chapter 1

Class Index

1.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

AdjacencyList	3
CommunityIdentifier	7
DijkstrasAlgorithm	7
GraphViz	8
KSimpleShortestPaths	9
MST	11
Parsing	13
PathInformation	15
SearchSpaceReduction	17
Utility	18

Chapter 2

Class Documentation

2.1 AdjacencyList Class Reference

```
#include <AdjacencyList.h>
```

Public Member Functions

- [AdjacencyList](#) ()
- [AdjacencyList](#) (int [size](#))
- [AdjacencyList](#) (int [size](#), int [vertexCount](#))
- void [resizeAdjList](#) (int [size](#), int [vertexCount](#))
- void [removeEdge](#) (int firstVertex, int secondVertex)
- void [addEdge](#) (int firstVertex, int secondVertex)
- void [updateInfo](#) (int vertexToUpdate, int value)
- int [getInfoValue](#) (int vertex) const
- void [setVertexConnections](#) (int vertex, std::vector< int > &vericesToAdd)
- std::vector< int > [getVertexConnections](#) (int vertex) const
- int [getVertexConnectionCount](#) (int vertex) const
- int [getVertexData](#) (int vertex, int index) const
- bool [validVertex](#) (int vertex) const
- int [size](#) () const
- int [vertexCount](#) () const
- std::string [displayAdjacencyList](#) () const
- void [saveToFile](#) (bool useNameList, std::map< int, std::string > nameList, std::string path)

2.1.1 Detailed Description

This class creates an array of linked lists to store data. The functions contained in it allow you to manipulate this array.

2.1.2 Constructor & Destructor Documentation

2.1.2.1 AdjacencyList::AdjacencyList ()

Default constructor that creates an adjacency list.

2.1.2.2 AdjacencyList::AdjacencyList (int [size](#))

Constructor that creates an adjacency list.

Parameters

<i>size</i>	Determines the size of the adjacency list
-------------	---

2.1.2.3 AdjacencyList::AdjacencyList (int *size*, int *vertexCount*)

Constructor that creates an adjacency list. The parameter *size* may be higher than *vertexCount* since not all vertices entered are not required to be in numerical order.

Parameters

<i>size</i>	Determines the size of the adjacency list
<i>vertexCount</i>	The number of vertices in the outer vector list

2.1.3 Member Function Documentation

2.1.3.1 void AdjacencyList::addEdge (int *firstVertex*, int *secondVertex*)

Adds an edge to the adjacencyList.

Parameters

<i>firstVertex</i>	The first half of the edge.
<i>secondVertex</i>	The second half of the edge.

2.1.3.2 std::string AdjacencyList::displayAdjacencyList () const

Gets a string containing the information in the adjacencyList.

Returns

a string that contains the information in the adjacencyList.

2.1.3.3 int AdjacencyList::getInfoValue (int *vertex*) const

Gets the value of a given vertex

Parameters

<i>vertex</i>	The vertex that you want to look up.
---------------	--------------------------------------

Returns

an integer that contains the value of a vertex.

2.1.3.4 int AdjacencyList::getVertexConnectionCount (int *vertex*) const

Gets the number of edges a given vertex has.

Parameters

<i>vertex</i>	The vertex that you want to look up.
---------------	--------------------------------------

Returns

an integer that contains the number of connections for the given vertex.

2.1.3.5 `std::vector< int > AdjacencyList::getVertexConnections (int vertex) const`

Gets a vector of vertices at a given vertex in the adjacency list.

Parameters

<i>vertex</i>	The vertex that you want to look up.
---------------	--------------------------------------

Returns

a vector<int> that contains the edges connected to a given vertex.

2.1.3.6 `int AdjacencyList::getVertexData (int vertex, int index) const`

Gets the value at the given vertex and index in the adjacencyList.

Parameters

<i>vertex</i>	The vertex in the adjacencyList to look at.
<i>index</i>	The position to get the value from.

Returns

an integer which is the value at the given vertex and index.

2.1.3.7 `void AdjacencyList::removeEdge (int firstVertex, int secondVertex)`

Removes an edge from the adjacencyList.

Parameters

<i>firstVertex</i>	The first half of the edge.
<i>secondVertex</i>	The second half of the edge.

2.1.3.8 `void AdjacencyList::resizeAdjList (int size, int vertexCount)`

Constructor that creates an adjacency list. The parameter size may be higher than vertexCount since not all vertices entered are not required to be in numerical order.

Parameters

<i>size</i>	Determines the size of the adjacency list
<i>vertexCount</i>	The number of vertices in the outer vector list

2.1.3.9 `void AdjacencyList::saveToFile (bool useNameList, std::map< int, std::string > nameList, std::string path)`

Saves the adjacencyList to a file.

Parameters

<i>useNameList</i>	Determines whether or not to save the information with name or integer values.
<i>nameList</i>	The map of integers to names to use if useNameList is True.
<i>path</i>	The path to save the file too. The path must include the file name.

2.1.3.10 void AdjacencyList::setVertexConnections (int *vertex*, std::vector< int > & *vericesToAdd*)

Adds all the vertices in *vericesToAdd* to the *adjacencyList* at *vertex*

Parameters

<i>vertex</i>	The vertex add connections to.
<i>vericesToAdd</i>	Vector of vertices to add.

2.1.3.11 int AdjacencyList::size () const

Gets the size of the *adjacencyList*.

Returns

an integer that contains the size of the *adjacencyList*.

2.1.3.12 void AdjacencyList::updateInfo (int *vertexToUpdate*, int *value*)

Changes the value of a vertex in the *infoList*.

Parameters

<i>vertexToUpdate</i>	The vertex to update in the <i>infoList</i> .
<i>value</i>	The second half of the edge.

2.1.3.13 bool AdjacencyList::validVertex (int *vertex*) const

Checks to see if a given vertex is within in the *adjacency list*.

Parameters

<i>vertex</i>	The vertex to search the <i>adjacency list</i> for.
---------------	---

Returns

True if the vertex is valid, False otherwise.

2.1.3.14 int AdjacencyList::vertexCount () const

Gets the number of vertices in the *adjacencyList*.

Returns

an integer that contains the number of vertices in the *adjacencyList*.

The documentation for this class was generated from the following files:

- Header_Files/AdjacencyList.h
- Source_Code/AdjacencyList.cpp

2.2 CommunityIdentifier Class Reference

```
#include <CommunityIdentifier.h>
```

Static Public Member Functions

- static [AdjacencyList](#) [identifyCommunities](#) (const [AdjacencyList](#) &adjacencyList, const std::vector< std::vector< int >> &keyVertices, int numVerticesFirstIter, int numVerticesSubsequentIter, int criticalVerticesNextIter, int depthToSearch)

2.2.1 Detailed Description

This class creates an [AdjacencyList](#) containing a subset nodes and edges from the adjacencylist. Nodes and edges are identified the KNV heuristic.

2.2.2 Member Function Documentation

2.2.2.1 [AdjacencyList](#) [CommunityIdentifier::identifyCommunities](#) (const [AdjacencyList](#) & *adjacencyList*, const std::vector< std::vector< int >> & *keyVertices*, int *numVerticesFirstIter*, int *numVerticesSubsequentIter*, int *criticalVerticesNextIter*, int *depthToSearch*) [static]

This function creates a reduced [AdjacencyList](#) that contains a subset of nodes and edges from the adjacencyList.

Parameters

<i>adjacencyList</i>	The data structure containing all nodes and edges.
<i>keyVertices</i>	Contains query vertices and path vertices.
<i>numVertices-FirstIter</i>	Controls how many vertices are included in the reduced adjacency list on the first depth level.
<i>numVertices-SubsequentIter</i>	Controls how many vertices are included in the reduced adjacency list on every depth level except the first.
<i>criticalVertices-NextIter</i>	Controls how many of the vertices in the current iteration are carried into the next iteration.
<i>depthToSearch</i>	Determines how many "hops" or edge connections away from a critical vertex to search.

The documentation for this class was generated from the following files:

- Header_Files/CommunityIdentifier.h
- Source_Code/CommunityIdentifier.cpp

2.3 DijkstrasAlgorithm Class Reference

Static Public Member Functions

- static void [singleSourceShortestPath](#) (int startVertex, int endVertex, [AdjacencyList](#) adjacencyList, [PathInformation](#) &pathInfo, int firstEdgeToDelete, int secondEdgeToDelete, bool removeEdge)

2.3.1 Member Function Documentation

2.3.1.1 void [DijkstrasAlgorithm::singleSourceShortestPath](#) (int *startVertex*, int *endVertex*, [AdjacencyList](#) *adjacencyList*, [PathInformation](#) & *pathInfo*, int *firstEdgeToDelete*, int *secondEdgeToDelete*, bool *removeEdge*) [static]

This function computes the shortest path from a start to end vertex.

Parameters

<i>startVertex</i>	The start point of the path to be calculated.
<i>endVertex</i>	The end point of the path to be calculated.
<i>adjacencyList</i>	An AdjacencyList that hold all the edges for each vertex.
<i>pathInfo</i>	Shortest path information will be stored in here.
<i>firstEdgeToDelete</i>	This is the vertex for the first half of the edge to delete.
<i>secondEdgeToDelete</i>	This is the vertex for the second half of the edge to delete.
<i>removeEdge</i>	This value determines whether or not to remove the edge given by <i>firstEdgeToDelete</i> and <i>secondEdgeToDelete</i> .

The documentation for this class was generated from the following files:

- Header_Files/DijkstrasAlgorithm.h
- Source_Code/DijkstrasAlgorithm.cpp

2.4 GraphViz Class Reference

```
#include <GraphViz.h>
```

Static Public Member Functions

- static void [convertKSSPAdjListToDOT](#) (const [AdjacencyList](#) &nonSearchReducedAdjList, const [AdjacencyList](#) &adjList, const std::vector< std::vector< int >> &keyVertices, const std::vector< [PathInformation](#) > &shortestPaths, const std::unordered_map< int, std::string > &nameList, bool useNameList, int colorSchemeFilter, std::string nodeSize, int edgeSchemeFilter, std::string dotFileLocation, std::string dotFileLocationDefaultFont, std::string adjListLocation)
- static void [convertMSTAdjListToDOT](#) (const [AdjacencyList](#) &nonSearchReducedAdjList, const [AdjacencyList](#) &adjList, const std::vector< std::vector< int >> &keyVertices, const std::vector< [PathInformation](#) > &shortestPaths, const std::unordered_map< int, std::string > &nameList, bool useNameList, int colorSchemeFilter, std::string nodeSize, int edgeSchemeFilter, std::string dotFileLocation, std::string dotFileLocationDefaultFont, std::string adjListLocation)

2.4.1 Detailed Description

This class creates a DOT and adjacency list file that contains information on the nodes and edges used to create the visualizations.

2.4.2 Member Function Documentation

2.4.2.1 void `GraphViz::convertKSSPAdjListToDOT (const AdjacencyList & nonSearchReducedAdjList, const AdjacencyList & adjList, const std::vector< std::vector< int >> & keyVertices, const std::vector< PathInformation > & shortestPaths, const std::unordered_map< int, std::string > & nameList, bool useNameList, int colorSchemeFilter, std::string nodeSize, int edgeSchemeFilter, std::string dotFileLocation, std::string dotFileLocationDefaultFont, std::string adjListLocation)` `[static]`

Creates a DOT and adjacency list file for the KSSP algorithm. This sets all visualization paramters.

Parameters

<i>nonSearch-ReducedAdjList</i>	This adj. list contains all the original edges and vertices from the dataset.
<i>adjList</i>	Reduced adj. list containing all the nodes and edges to be visualized.
<i>keyVertices</i>	Contains the query and path vertices.
<i>shortestPaths</i>	Contains the shortest paths.
<i>nameList</i>	Contains the mapping from integer to name.
<i>useNameList</i>	Determines whether or not to map an integer to a name.
<i>colorScheme-Filter</i>	Determines which vertex color scheme to use.
<i>nodeSize</i>	Determines the vertex size
<i>edgeScheme-Filter</i>	Determines whether the edges are gray or colored.
<i>dotFileLocation</i>	The path to save the DOT file.
<i>dotFileLocation-DefaultFont</i>	The path to save the second DOT file.
<i>adjListLocation</i>	The path to save the adjacency list.

```
2.4.2.2 void GraphViz::convertMSTAdjListToDOT ( const AdjacencyList & nonSearchReducedAdjList, const
AdjacencyList & adjList, const std::vector< std::vector< int >> & keyVertices, const std::vector<
PathInformation > & shortestPaths, const std::unordered_map< int, std::string > & nameList, bool useNameList,
int colorSchemeFilter, std::string nodeSize, int edgeSchemeFilter, std::string dotFileLocation, std::string
dotFileLocationDefaultFont, std::string adjListLocation ) [static]
```

Creates a DOT and adjacency list file for the [MST](#) algorithm. This sets all visualization parameters.

Parameters

<i>nonSearch-ReducedAdjList</i>	This adj. list contains all the original edges and vertices from the dataset.
<i>adjList</i>	Reduced adj. list containing all the nodes and edges to be visualized.
<i>keyVertices</i>	Contains the query and path vertices.
<i>shortestPaths</i>	Contains the shortest paths.
<i>nameList</i>	Contains the mapping from integer to name.
<i>useNameList</i>	Determines whether or not to map an integer to a name.
<i>colorScheme-Filter</i>	Determines which vertex color scheme to use.
<i>nodeSize</i>	Determines the vertex size
<i>edgeScheme-Filter</i>	Determines whether the edges are gray or colored.
<i>dotFileLocation</i>	The path to save the DOT file.
<i>dotFileLocation-DefaultFont</i>	The path to save the second DOT file.
<i>adjListLocation</i>	The path to save the adjacency list.

The documentation for this class was generated from the following files:

- Header_Files/GraphViz.h
- Source_Code/GraphViz.cpp

2.5 KSimpleShortestPaths Class Reference

```
#include <KSimpleShortestPaths.h>
```

Static Public Member Functions

- static int **runKSSP** (const [AdjacencyList](#) &adjacencyList, std::vector< std::string > programInfo, std::ofstream &output, bool debug, std::unordered_map< std::string, int > nameListKey, std::unordered_map< int, std::string > nameList, bool useKSSP)
- static void **kSSP** (int startVertex, int endVertex, int numberOfPathsToCalc, [AdjacencyList](#) adjacencyList, std::vector< [PathInformation](#) > &kShortestPaths, bool &validPathFound, std::ofstream &output, bool debug)
- static void **kSSPR** (int startVertex, int endVertex, int numberOfPathsToCalc, [AdjacencyList](#) adjacencyList, int depthToSearch, bool debug, std::vector< [PathInformation](#) > &kShortestPaths, bool &validPathFound, int numVerticesFirstlter, int numVerticesSubsequentlter, int criticalVerticesNextlter, int numVerticesFirstlter2, int numVerticesSubsequentlter2, int criticalVerticesNextlter2, int depthSSR2, std::ofstream &output, bool searchSpaceReduce)

2.5.1 Detailed Description

This class finds the paths from one vertex to another. There exists both a single threaded and multi-threaded variation.

2.5.2 Member Function Documentation

2.5.2.1 void `KSimpleShortestPaths::kSSP (int startVertex, int endVertex, int numberOfPathsToCalc, AdjacencyList adjacencyList, std::vector< PathInformation > & kShortestPaths, bool & validPathFound, std::ofstream & output, bool debug)` `[static]`

Computes the K-Simple Shortest Paths in single threaded mode.

Parameters

<i>startVertex</i>	This is the start of the path that all calculations will originate.
<i>endVertex</i>	This is the end destination that all paths will converge to.
<i>numberOfPathsToCalc</i>	This is the number of paths to calculate.
<i>adjacencyList</i>	Contains the graph information.
<i>kShortestPaths</i>	Contains the information for each shortest path found.
<i>validPathFound</i>	True if a path was found, false otherwise.
<i>output</i>	An ofstream reference to print time measurements to a file.
<i>debug</i>	If true, measure the run time of the program.

2.5.2.2 void `KSimpleShortestPaths::kSSPR (int startVertex, int endVertex, int numberOfPathsToCalc, AdjacencyList adjacencyList, int depthToSearch, bool debug, std::vector< PathInformation > & kShortestPaths, bool & validPathFound, int numVerticesFirstlter, int numVerticesSubsequentlter, int criticalVerticesNextlter, int numVerticesFirstlter2, int numVerticesSubsequentlter2, int criticalVerticesNextlter2, int depthSSR2, std::ofstream & output, bool searchSpaceReduce)` `[static]`

Computes the K-Simple Shortest Paths in multi-threaded mode.

Parameters

<i>startVertex</i>	This is the start of the path that all calculations will originate.
<i>endVertex</i>	This is the end destination that all paths will converge to.
<i>numberOfPathsToCalc</i>	This is the number of paths to calculate.

<i>adjacencyList</i>	Contains the graph information.
<i>depthToSearch</i>	The depth to search for the first search space reduction (SSR1).
<i>debug</i>	If true, measure the run time of the program.
<i>kShortestPaths</i>	Contains the information for each shortest path found.
<i>validPathFound</i>	True if a path was found, false otherwise.
<i>numVertices-FirstIter</i>	Controls how many vertices are included in the reduced adjacency list on the first depth level (SSR1).
<i>numVertices-SubsequentIter</i>	Controls how many vertices are included in the reduced adjacency list on every depth level except the first (SSR1).
<i>criticalVertices-NextIter</i>	Controls how many of the vertices in the current iteration are carried into the next iteration (SSR1).
<i>numVertices-FirstIter2</i>	Controls how many vertices are included in the reduced adjacency list on the first depth level (SSR2).
<i>numVertices-SubsequentIter2</i>	Controls how many vertices are included in the reduced adjacency list on every depth level except the first (SSR2).
<i>criticalVertices-NextIter2</i>	Controls how many of the vertices in the current iteration are carried into the next iteration (SSR2).
<i>depthSSR2</i>	The depth to search for the first search space reduction (SSR2).
<i>output</i>	An ofstream reference to print time measurements to a file.
<i>searchSpace-Reduce</i>	Determines whether or not to use the search space reduction algorithm.

```
2.5.2.3 int KSimpleShortestPaths::runKSSP ( const AdjacencyList & adjacencyList, std::vector< std::string > programInfo,
std::ofstream & output, bool debug, std::unordered_map< std::string, int > nameListKey, std::unordered_map< int,
std::string > nameList, bool useKSSP ) [static]
```

Runs the KSSP calculations, creates DOT and adjacency list of results.

Parameters

<i>adjacencyList</i>	Contains the graph information.
<i>programInfo</i>	Contains arguments to program.
<i>output</i>	An ofstream reference to print time measurements to a file.
<i>debug</i>	If true, measure the run time of the program.
<i>nameListKey</i>	Creates a map between the string and integer representation of the data.
<i>nameList</i>	Creates a map between the integer and string representation of the data.
<i>useKSSP</i>	Determines whether or not to use single threaded non-search reduced version of KSSP or multithreaded search reduced version.

Returns

int The status of the program calculations.

The documentation for this class was generated from the following files:

- Header_Files/KSimpleShortestPaths.h
- Source_Code/KSimpleShortestPaths.cpp

2.6 MST Class Reference

```
#include <MST.h>
```

Static Public Member Functions

- static int `runMST` (const [AdjacencyList](#) &adjacencyList, std::vector< std::string > programInfo, std::ofstream &output, bool debug, std::unordered_map< std::string, int > nameListKey, std::unordered_map< int, std::string > nameList)
- static std::vector< [PathInformation](#) > `calculateMST` (const [AdjacencyList](#) &adjacencyList, const std::vector< int > &verticesToSearch, int depthToSearch, bool debug, int numVerticesFirstIter, int numVerticesSubsequentIter, int criticalVerticesNextIter, std::ofstream &output, bool searchSpaceReduce)

2.6.1 Detailed Description

This class finds a [MST](#) using shortest paths between a set of user specified query nodes.

2.6.2 Member Function Documentation

2.6.2.1 `std::vector< PathInformation > MST::calculateMST (const AdjacencyList & adjacencyList, const std::vector< int > & verticesToSearch, int depthToSearch, bool debug, int numVerticesFirstIter, int numVerticesSubsequentIter, int criticalVerticesNextIter, std::ofstream & output, bool searchSpaceReduce) [static]`

Creates a [MST](#) between a set of user specified query nodes.

Parameters

<i>adjacencyList</i>	Contains the graph information.
<i>verticesToSearch</i>	The set of user specified query nodes
<i>depthToSearch</i>	The depth to search for the first search space reduction (SSR1).
<i>debug</i>	If true, measure the run time of the program.
<i>numVerticesFirstIter</i>	Controls how many vertices are included in the reduced adjacency list on the first depth level (SSR1).
<i>numVerticesSubsequentIter</i>	Controls how many vertices are included in the reduced adjacency list on every depth level except the first (SSR1).
<i>criticalVerticesNextIter</i>	Controls how many of the vertices in the current iteration are carried into the next iteration (SSR1).
<i>searchSpaceReduce</i>	Determines whether or not to use the search space reduction algorithm.
<i>output</i>	An ofstream reference to print time measurements to a file.

Returns

[PathInformation](#) containing the [MST](#) between the query nodes.

2.6.2.2 `int MST::runMST (const AdjacencyList & adjacencyList, std::vector< std::string > programInfo, std::ofstream & output, bool debug, std::unordered_map< std::string, int > nameListKey, std::unordered_map< int, std::string > nameList) [static]`

Runs the [MST](#) calculations, creates DOT and adjacency list of results.

Parameters

<i>adjacencyList</i>	Contains the graph information.
----------------------	---------------------------------

<i>programInfo</i>	Contains arguments to program.
<i>output</i>	An ofstream reference to print time measurements to a file.
<i>debug</i>	If true, measure the run time of the program.
<i>nameListKey</i>	Creates a map between the string and integer representation of the data.
<i>nameList</i>	Creates a map between the integer and string representation of the data.

Returns

int The status of the program calculations.

The documentation for this class was generated from the following files:

- Header_Files/MST.h
- Source_Code/MST.cpp

2.7 Parsing Class Reference

Static Public Member Functions

- static void [getGraphData](#) (std::string pathToDatasetFile, [AdjacencyList](#) &adjacencyList)
- static void [getNamedGraphData](#) (std::string pathToDatasetFile, [AdjacencyList](#) &adjacencyList, std::unordered_map< int, std::string > &nameList, std::unordered_map< std::string, int > &nameListKey)
- static void [removeVertices](#) ([AdjacencyList](#) &adjacencyList, const std::unordered_map< std::string, int > &nameListKey, const std::vector< std::string > &programInfo, bool useNameList)
- static void [removeEdges](#) ([AdjacencyList](#) &adjacencyList, const std::unordered_map< std::string, int > &nameListKey, const std::vector< std::string > &programInfo, bool useNameList)
- static void [parseMSTResults](#) (const std::vector< [PathInformation](#) > &mstShortestPaths, const std::vector< int > &MSTVertices, std::vector< std::vector< int >> &keyVertices, std::ofstream &output)
- static void [parseKSSPResults](#) (std::vector< std::vector< int >> &keyVertices, const std::vector< [PathInformation](#) > &shortestPaths, int startVertex, int endVertex)

2.7.1 Member Function Documentation

2.7.1.1 void [Parsing::getGraphData](#) (std::string *pathToDatasetFile*, [AdjacencyList](#) & *adjacencyList*) [static]

Reads in integer graph data.

Parameters

<i>pathToDatasetFile</i>	Path to the dataset.
<i>adjacencyList</i>	Data structure to hold all the dataset information.

2.7.1.2 void [Parsing::getNamedGraphData](#) (std::string *pathToDatasetFile*, [AdjacencyList](#) & *adjacencyList*, std::unordered_map< int, std::string > & *nameList*, std::unordered_map< std::string, int > & *nameListKey*) [static]

Reads in string graph data.

Parameters

<i>pathToDataset-File</i>	Path to the dataset.
<i>adjacencyList</i>	Data structure to hold all the dataset information.
<i>nameList</i>	Creates a map between the integer and string representation of the data.
<i>nameListKey</i>	Creates a map between the string and integer representation of the data.

2.7.1.3 `void Parsing::parseKSSPResults (std::vector< std::vector< int >> & keyVertices, const std::vector< PathInformation > & shortestPaths, int startVertex, int endVertex) [static]`

Takes the KSSP information and parses the paths.

Parameters

<i>keyVertices</i>	Stores the path and query vertices.
<i>shortestPaths</i>	Contains the shortest paths.
<i>startVertex</i>	The start vertex.
<i>endVertex</i>	The end vertex.

2.7.1.4 `void Parsing::parseMSTResults (const std::vector< PathInformation > & mstShortestPaths, const std::vector< int > & MSTVertices, std::vector< std::vector< int >> & keyVertices, std::ofstream & output) [static]`

Takes the [MST](#) information and parses the path and query vertices.

Parameters

<i>mstShortest-Paths</i>	Contains the MST path information.
<i>MSTVertices</i>	Contains the MST query vertices.
<i>keyVertices</i>	Stores the path and query vertices.
<i>output</i>	An ofstream reference to print time measurements to a file.

2.7.1.5 `void Parsing::removeEdges (AdjacencyList & adjacencyList, const std::unordered_map< std::string, int > & nameListKey, const std::vector< std::string > & programInfo, bool useNameList) [static]`

Removes user specified edges from the adjacency list.

Parameters

<i>adjacencyList</i>	Data structure to have information removed from.
<i>nameListKey</i>	Creates a map between the string and integer
<i>programInfo</i>	Contains the user specified edges to remove from the adjacency list.
<i>useNameList</i>	Determines whether or not to use the nameList mapping.

2.7.1.6 `void Parsing::removeVertices (AdjacencyList & adjacencyList, const std::unordered_map< std::string, int > & nameListKey, const std::vector< std::string > & programInfo, bool useNameList) [static]`

Removes user specified vertices from the adjacency list.

Parameters

<i>adjacencyList</i>	Data structure to have information removed from.
----------------------	--

<i>nameListKey</i>	Creates a map between the string and integer
<i>programInfo</i>	Contains the user specified vertices to remove from the adjacency list.
<i>useNameList</i>	Determines whether or not to use the nameList mapping.

The documentation for this class was generated from the following files:

- Header_Files/Parsing.h
- Source_Code/Parsing.cpp

2.8 PathInformation Class Reference

```
#include <PathInformation.h>
```

Public Member Functions

- [PathInformation](#) ()
- [PathInformation](#) (std::vector< int > path, int pathLength)
- std::vector< int > [getPath](#) () const
- int [getPathAt](#) (int index) const
- int [getPathLength](#) () const
- void [setPath](#) (std::vector< int > updatedPath)
- void [setPathLength](#) (int updatedPathLength)
- std::string [toString](#) () const
- bool [equals](#) ([PathInformation](#) other) const

2.8.1 Detailed Description

This class stores and manipulates data for a string and integer

2.8.2 Constructor & Destructor Documentation

2.8.2.1 PathInformation::PathInformation ()

Constructor. Creates an empty string for path and sets pathLength to 0.

2.8.2.2 PathInformation::PathInformation (std::vector< int > path, int pathLength)

Constructor.

Parameters

<i>path</i>	Initializes path with path.
<i>pathLength</i>	Initializes the pathLength with pathLength.

2.8.3 Member Function Documentation

2.8.3.1 bool PathInformation::equals (PathInformation other) const

Compares two [PathInformation](#) objects.

Returns

true if the paths are equal, false otherwise

2.8.3.2 `std::vector< int > PathInformation::getPath () const`

Gets the path.

Returns

vector Containing the path information.

2.8.3.3 `int PathInformation::getPathAt (int index) const`

Gets the path information at a given index.

Returns

int The value at the index in the path.

2.8.3.4 `int PathInformation::getPathLength () const`

Returns the path length

Returns

integer The length of the path.

2.8.3.5 `void PathInformation::setPath (std::vector< int > updatedPath)`

Sets the path

Parameters

<i>updatedPath</i>	Sets the path to updatedPath.
--------------------	-------------------------------

2.8.3.6 `void PathInformation::setPathLength (int updatedPathLength)`

Sets the path length

Parameters

<i>updatedPath- Length</i>	Sets the pathLength to updatedPathLength.
--------------------------------	---

2.8.3.7 `std::string PathInformation::toString () const`

Returns the path and pathLength

Returns

a string that contains the path and pathLength

The documentation for this class was generated from the following files:

- `Header_Files/PathInformation.h`
- `Source_Code/PathInformation.cpp`

2.9 SearchSpaceReduction Class Reference

```
#include <SearchSpaceReduction.h>
```

Static Public Member Functions

- static void [searchSpaceReduce](#) (const [AdjacencyList](#) &adjacencyList, [AdjacencyList](#) &reducedAdjacencyList, const [PathInformation](#) &pathToSearch, int depthToSearch, int numVerticesFirstIter, int numVerticesSubsequentIter, int criticalVerticesNextIter)
- static void [keyNeighboringVertices](#) (const [AdjacencyList](#) &adjacencyList, const [PathInformation](#) &pathToSearch, [AdjacencyList](#) &updatedAdjacencyList, int ¤tDepth, int depthToSearch, int averageCentrality, int numVerticesFirstIter, int numVerticesSubsequentIter, int criticalVerticesNextIter)

2.9.1 Detailed Description

This class creates a subset of the original graph to reduce the search space and computation time of the network connectivity algorithms.

2.9.2 Member Function Documentation

2.9.2.1 void SearchSpaceReduction::keyNeighboringVertices (const [AdjacencyList](#) & *adjacencyList*, const [PathInformation](#) & *pathToSearch*, [AdjacencyList](#) & *updatedAdjacencyList*, int & *currentDepth*, int *depthToSearch*, int *averageCentrality*, int *numVerticesFirstIter*, int *numVerticesSubsequentIter*, int *criticalVerticesNextIter*)
[static]

This function determines which vertices and edges are important in the graph.

Parameters

<i>adjacencyList</i>	Contains the graph information.
<i>pathToSearch</i>	Contains the important vertices to search in the vicinity of.
<i>updated-AdjacencyList</i>	Contains the reduced adjacency list with all vertices and edges identified as 'key'.
<i>currentDepth</i>	The current depth that the program is at in the breadth first search of the network.
<i>average-Centrality</i>	The average degree centrality of the network.
<i>numVertices-FirstIter</i>	Controls how many vertices are included in the reduced adjacency list on the first depth level.
<i>numVertices-SubsequentIter</i>	Controls how many vertices are included in the reduced adjacency list on every depth level except the first.
<i>criticalVertices-NextIter</i>	Controls how many of the vertices in the current iteration are carried into the next iteration.
<i>depthToSearch</i>	Determines how many "hops" or edge connections away from a critical vertex to search.

2.9.2.2 void SearchSpaceReduction::searchSpaceReduce (const [AdjacencyList](#) & *adjacencyList*, [AdjacencyList](#) & *reducedAdjacencyList*, const [PathInformation](#) & *pathToSearch*, int *depthToSearch*, int *numVerticesFirstIter*, int *numVerticesSubsequentIter*, int *criticalVerticesNextIter*) [static]

Reduces the search space and computation time of the network connectivity algorithms.

Parameters

<i>adjacencyList</i>	The data structure containing all nodes and edges.
<i>reduced-AdjacencyList</i>	This will be the search space reduced adj. list containing the key nodes and edges.
<i>pathToSearch</i>	Contains the important vertices to search in the vicinity of.
<i>depthToSearch</i>	Determines how many "hops" or edge connections away from a critical vertex to search.
<i>numVertices-FirstIter</i>	Controls how many vertices are included in the reduced adjacency list on the first depth level.
<i>numVertices-SubsequentIter</i>	Controls how many vertices are included in the reduced adjacency list on every depth level except the first.
<i>criticalVertices-NextIter</i>	Controls how many of the vertices in the current iteration are carried into the next iteration.

The documentation for this class was generated from the following files:

- Header_Files/SearchSpaceReduction.h
- Source_Code/SearchSpaceReduction.cpp

2.10 Utility Class Reference

```
#include <Utility.h>
```

Static Public Member Functions

- static int [vectorIntersection](#) (std::vector< int > v1, std::vector< int > v2)
- static bool [vectorIntIntersection](#) (const std::vector< int > &v1, int v2)
- static std::string [vectorToString](#) (std::vector< int > &v1)

2.10.1 Detailed Description

This class contains helper functions that are used to manipulate vectors.

2.10.2 Member Function Documentation

2.10.2.1 int [Utility::vectorIntersection](#) (std::vector< int > v1, std::vector< int > v2) [static]

Determines the number of elements that two vectors have in common.

Parameters

<i>v1</i>	The first vector.
<i>v2</i>	The second vector.

Returns

integer containing the number of intersected elements.

2.10.2.2 bool [Utility::vectorIntIntersection](#) (const std::vector< int > &v1, int v2) [static]

Determines if an integer exists in a vector.

Parameters

<i>v1</i>	The vector.
<i>v2</i>	The integer.

Returns

bool True if it's found, false otherwise

2.10.2.3 `std::string Utility::vectorToString (std::vector< int > & v1) [static]`

Converts a vector to a string.

Parameters

<i>v1</i>	The vector.
-----------	-------------

Returns

string containing the vector information.

The documentation for this class was generated from the following files:

- Header_Files/Utility.h
- Source_Code/Utility.cpp

Index

- addEdge
 - AdjacencyList, 4
- AdjacencyList, 3
 - addEdge, 4
 - AdjacencyList, 3, 4
 - AdjacencyList, 3, 4
 - displayAdjacencyList, 4
 - getInfoValue, 4
 - getVertexConnectionCount, 4
 - getVertexConnections, 5
 - getVertexData, 5
 - removeEdge, 5
 - resizeAdjList, 5
 - saveToFile, 5
 - setVertexConnections, 6
 - size, 6
 - updateInfo, 6
 - validVertex, 6
 - vertexCount, 6
- calculateMST
 - MST, 12
- CommunityIdentifier, 7
 - identifyCommunities, 7
- convertKSSPAdjListToDOT
 - GraphViz, 8
- convertMSTAdjListToDOT
 - GraphViz, 9
- DijkstrasAlgorithm, 7
 - singleSourceShortestPath, 7
- displayAdjacencyList
 - AdjacencyList, 4
- equals
 - PathInformation, 15
- getGraphData
 - Parsing, 13
- getInfoValue
 - AdjacencyList, 4
- getNamedGraphData
 - Parsing, 13
- getPath
 - PathInformation, 15
- getPathAt
 - PathInformation, 16
- getPathLength
 - PathInformation, 16
- getVertexConnectionCount
 - AdjacencyList, 4
- getVertexConnections
 - AdjacencyList, 5
- getVertexData
 - AdjacencyList, 5
- GraphViz, 8
 - convertKSSPAdjListToDOT, 8
 - convertMSTAdjListToDOT, 9
- identifyCommunities
 - CommunityIdentifier, 7
- kSSP
 - KSimpleShortestPaths, 10
- kSSPR
 - KSimpleShortestPaths, 10
- KSimpleShortestPaths, 9
 - kSSP, 10
 - kSSPR, 10
 - runKSSP, 11
- keyNeighboringVertices
 - SearchSpaceReduction, 17
- MST, 11
 - calculateMST, 12
 - runMST, 12
- parseKSSPResults
 - Parsing, 14
- parseMSTResults
 - Parsing, 14
- Parsing, 13
 - getGraphData, 13
 - getNamedGraphData, 13
 - parseKSSPResults, 14
 - parseMSTResults, 14
 - removeEdges, 14
 - removeVertices, 14
- PathInformation, 15
 - equals, 15
 - getPath, 15
 - getPathAt, 16
 - getPathLength, 16
 - PathInformation, 15
 - PathInformation, 15
 - setPath, 16
 - setPathLength, 16
 - toString, 16
- removeEdge
 - AdjacencyList, 5

- removeEdges
 - Parsing, 14
- removeVertices
 - Parsing, 14
- resizeAdjList
 - AdjacencyList, 5
- runKSSP
 - KSimpleShortestPaths, 11
- runMST
 - MST, 12

- saveToFile
 - AdjacencyList, 5
- searchSpaceReduce
 - SearchSpaceReduction, 17
- SearchSpaceReduction, 17
 - keyNeighboringVertices, 17
 - searchSpaceReduce, 17
- setPath
 - PathInformation, 16
- setPathLength
 - PathInformation, 16
- setVertexConnections
 - AdjacencyList, 6
- singleSourceShortestPath
 - DijkstrasAlgorithm, 7
- size
 - AdjacencyList, 6

- toString
 - PathInformation, 16

- updateInfo
 - AdjacencyList, 6
- Utility, 18
 - vectorIntIntersection, 18
 - vectorIntersection, 18
 - vectorToString, 19

- validVertex
 - AdjacencyList, 6
- vectorIntIntersection
 - Utility, 18
- vectorIntersection
 - Utility, 18
- vectorToString
 - Utility, 19
- vertexCount
 - AdjacencyList, 6